AHM3

Magnetic Analog Absolute Single Turn Encoders



Features

 With its 30mm size and a 6mm solid shaft, AHM3 encoder characterizes itself by its strong robustness of the mechanical and electro-magnetic parts, it's the most compact really industrial encoder with a solid shaft.

Sensata

Technologies

- Application fields : agriculture, construction, forestry vehicles, medical applications, solar panels...
- Magnetic technology, contactless.
- Available resolution up to 12 bits per revolution.
- Universal supply 5 to 30Vdc available.
- Also available : analog, PWM and SSI outputs..
- Available in option : Extended temperature range (up to -40..+125°C), IP67/IP69K...



Mechanical Data

Material	Shaft: stainless steel, Cover: aluminium, Body: aluminium							
Bearings	696 series							
Maximal loads	Axial : 20 N, Radial : 50 N							
Shaft inertia	$\leq 0, 1.10^{-6} \text{ kg.m}^2$							
Torque	≤ 1.10 ⁻³ N.m							
Nominal max. speed	6 000 min ⁻¹							
Encoder weight (approx.)	0,150 kg							
Isolation	500Veff							
EMC	EN 61000-6-4, EN 61000-6-2							
Operating temperature	- 40 + 85 °C (encoder T°)							
Storage temperature	- 40 + 85 °C							
Protection	IP 65							
Shocks (EN60068-2-27)	\leq 2000m.s ² (during 6 ms)							
Vibrations (EN60068-2-6)	≤ 200m.s ⁻² (55 2 000 Hz)							
Theoretical mechanical lifetime	10º turns (Faxial / Fradial)							
20 N / 50 N	15							
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Electrical Data

Power supply	5-30Vdc
Comsumption without load	< 40mA (at 24Vdc)
Resolution	4096 (2 ¹²)
Accuracy	± 0.3 %
Repeatability	± 0.1 %
Introduction	<1s
Refresh rate	< 400µs



TECHNICAL SPECIFICATIONS

Programmable Parameters

Resolution: defines the resolution per revolution (0 à 4 096).
Transmission speed: programmable from 10kBaud (1 000m) to 1 Mbaud (25 m) ; value per default : 20 Kbaud.
Address: defines the software address of the encoder on the bus (1 à 127, Value per default : id = 1).
Direction: defines the direction of count of the encoder.
RAX: define the value of the current position (stationnary shaft).
Cames: high and low limits.

Communication Modes

Encoder configuration: Reading/Writing of the encoder objects dictionnary (SDO mode).

3 modes are available to interrogate the encoder position/speed :

CYCLIC mode: the encoder transmits its position in an asynchronous manner.

The frequency of the transmission is defined by the programmable cyclic timer register from 0 to 65 535 ms,

SYNCHRO mode: the encoder transmits its position on a synchronous demand by the master.

POOLING mode (Answer to a RTR signal): the encoder only answers to a request.

Connectique Canopen

Туре	Description	OV	+Vcc	CAN GND / OV	CAN HIGH	CAN LOW	Ground
BB	PVC cable + DB9	6	9	3	7	2	Connector body
B7	M12 5 pinouts	1	2	3	4	5	Connector body

Note :

-Refer to the bus standards for the maximal derivation,

- signals OV and CAN GND are connected together (internally);





AHM3 B7A connection (Axial M12 output)







Example : AHM3-06-P-1-BB-B-12-BB-D020

(Contact the factory for special versions , ex : dimensions, connections...) Made in France

Family	AHM3	 06	-	Р	-	BB	_	В	Ξ.	12	-	BB	D020
AHIVIJ													
Shaft Ø													
06 = 6mm													
Supply													
P = 5 to 30Vdc													
Output stage													
BB = CANopen													
Code	-												
B = Binary													
Resolution													
12 = 4096 (2 ¹²)													
Connection													
BB = PVC Cable + DB9 C B7 = M12 5 pinouts	CAN- open												
Connection orier	ntation												
D020 = Diagonal Cable 2 A = Axial	2m												







DANGER

RISK OF MATERIAL DAMAGE AND HOT ENCLOSURE

- The product's side panels may be hot, allow the product to cool before touching
- Follow proper mounting instructions including torque values
- Do not allow liquids or foreign objects to enter this product

Failure to follow these instructions can result in serious injury, or equipment damage.



HAZARD OF ELECTRIC SHOCK, EXPLOSION OR ARCH FLASH • Disconnect all power before installing or working with this equipment

Verify all connections and replace all covers before turning on power

Failure to follow these instructions will result in death or serious injury

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